

# An $n \log n$ Heuristic for the TSP

Éric D. Taillard

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# TSP Stat of the Art

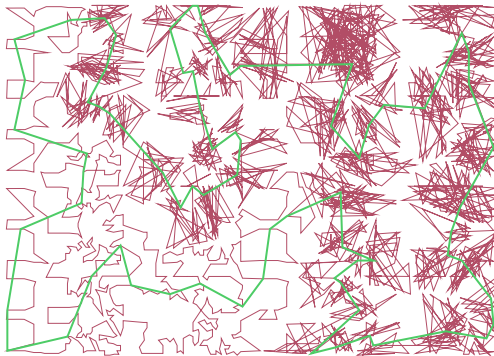
- "Exact" algorithms
  - Concorde (Applegate, Bixby, Chvátal, Cook, 2003 [1])
  - Optimum known for  $\approx 100k$  cities instances
- Heuristics
  - Local search with Lin & Kernighan (1973) [9] neighbourhood
    - + k-opt moves(algorithmic complexity:  $k = 5 \implies O(n^{4 \cdot k})$ )
    - + neighbourhood reduction (keep  $\approx 5$  adjacent edges for each city)
    - + iterated random perturbations (double bridge)
  - One of the best algorithms due to K. Helsgaun (LKH, 2000–2018 [4, 5, 3, 7, 8])
  - Solutions less than 0.0...% above optimum for all instances of the litterature (up to  $10^7$  cities)

# Tours merging strategy

- Generate rapidly several different, moderately good tours (few dozens)
- Build a partial graph containing only the edges of these tours
- Apply a local search limited to the edges of the partial graph
  - Known process, allowing to get good solutions (Blazinskas et Misevicius (2012) [2])
- Difficulty: How to get moderately good solutions for non Euclidean instances with a limited complexity ( $< O(n^2)$ )

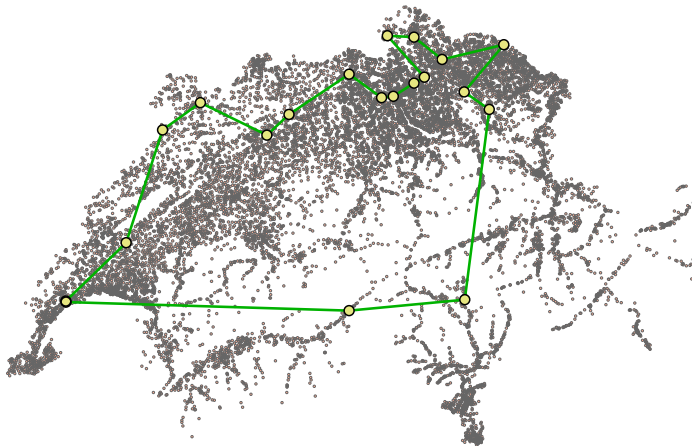
# Method in $O(n^{1.57})$ (MIC 2017, EJOR 2019 [10, 11])

- Select a sample of  $O(n^{0.56})$  cities
- Find a good tour on the sample with Lin-Kernighan neighbourhood
- Group all the cities into a number of clusters equals to the sample
- Optimize the tour with 2-opt neighbourhood by considering 2 successive clusters at a time
- Re-optimize the tour with POPMUSIC (all subsets of 50 successive cities are local optimum)



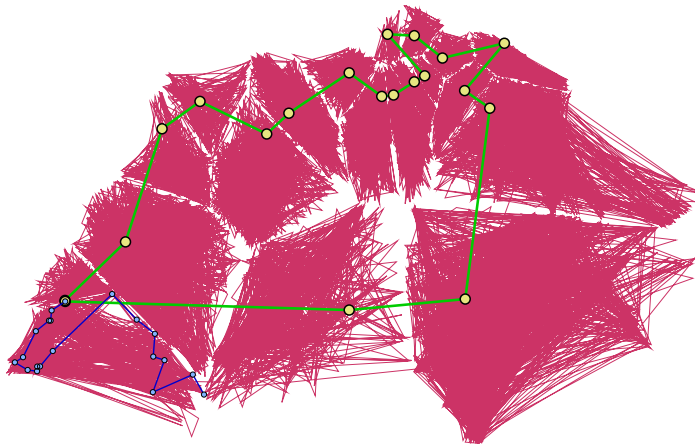
# New Method in $n \log n$

- Recursive decomposition with a fixed sample size  $t$



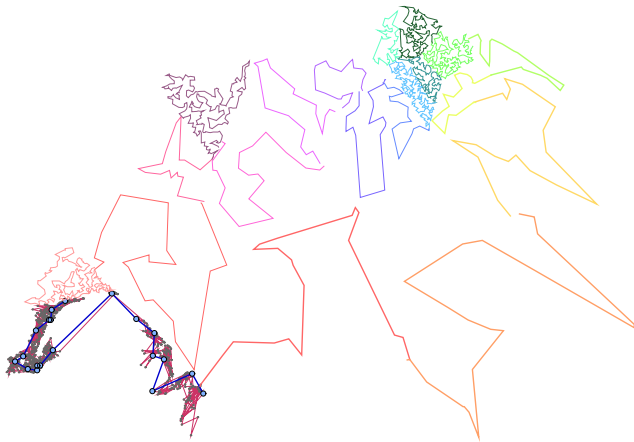
# First complete solution obtained in linear time

- Clusters that are larger than  $t^2$  are decomposed into  $t$  clusters

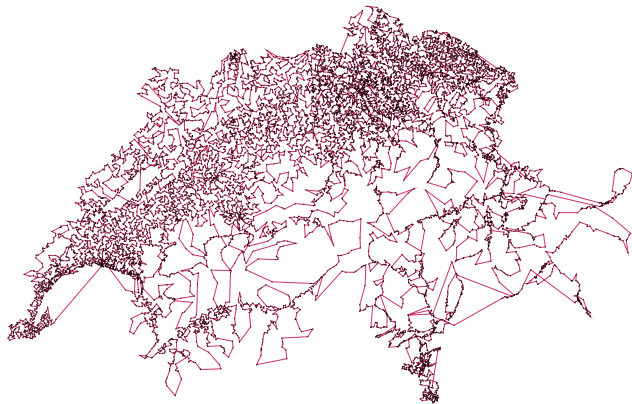


# Iterate until cluster size $< t^2$

- A good path for a cluster with few hundreds of cities can be rapidly obtained with Lin-Kernighan neighbourhood



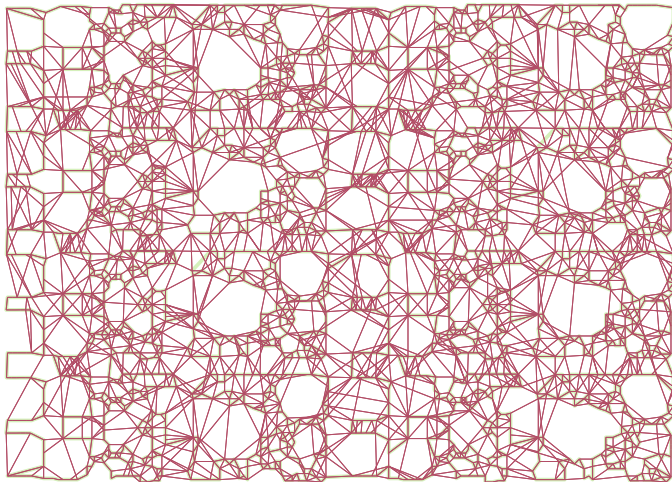
# Solution finally built



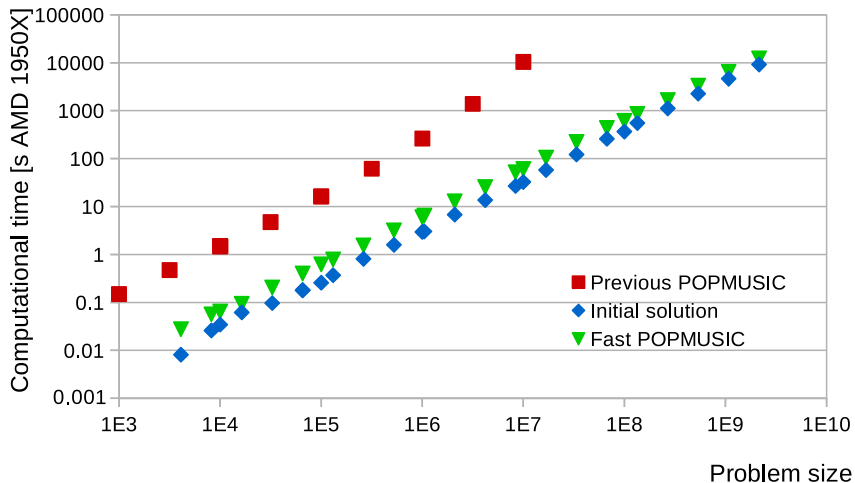
- The solution is improved with a fast POPMUSIC
  - Non-overlapping paths with  $t^2$  cities are independently optimized
  - Only 2 scans, shifted by  $t^2/2$  cities



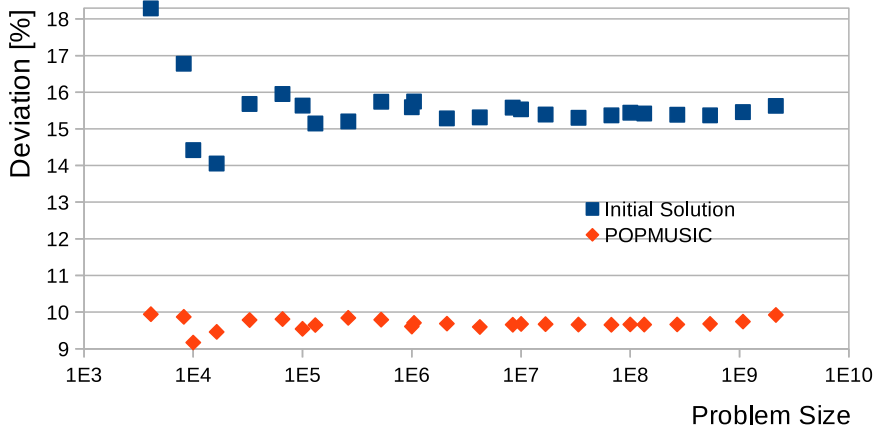
# Union 20 solutions superimposed to an optimal solution



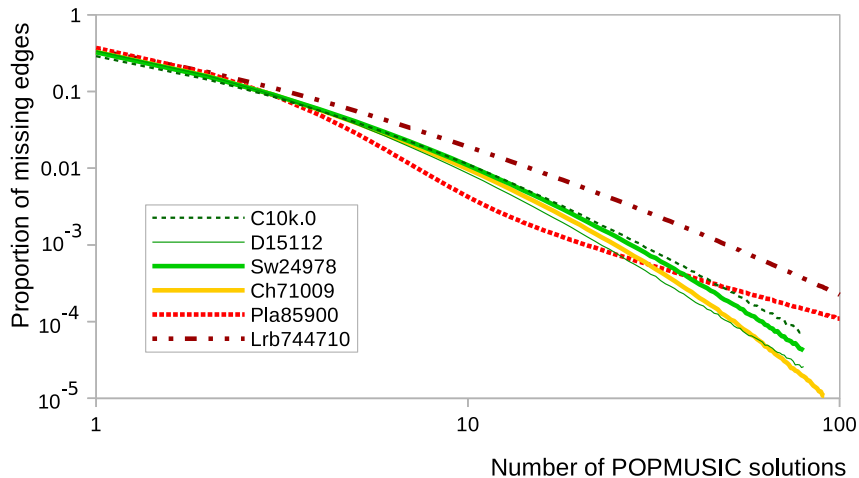
# Computational time as a function of problem size



# Solution quality for 2D toroidal instances

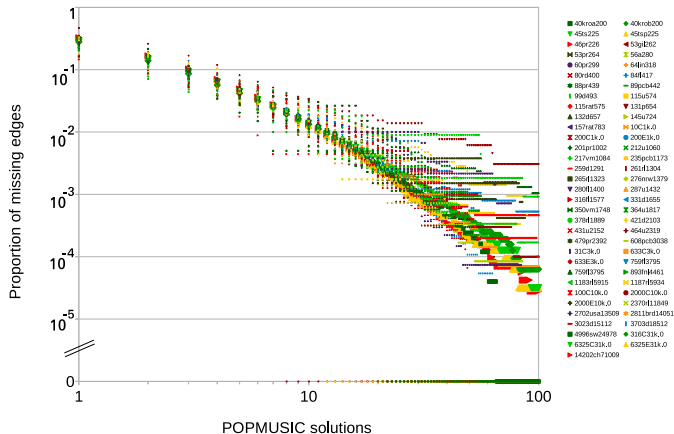


# Proportion of missing edges relatively to best solutions



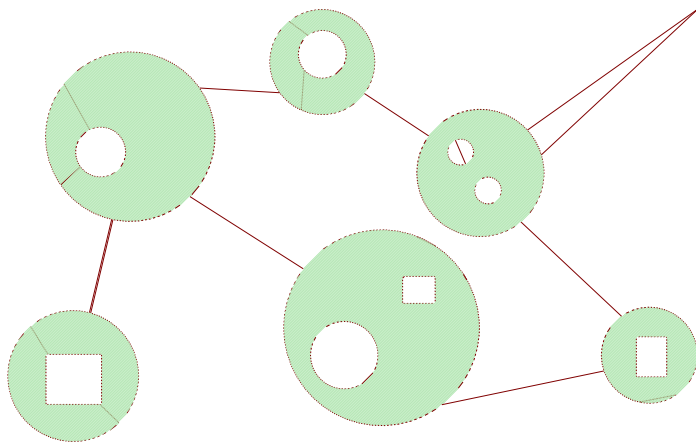
# Application to the Clustered TSP

Proportion of edges missing from best solutions (Helsgaun 2014 [6])



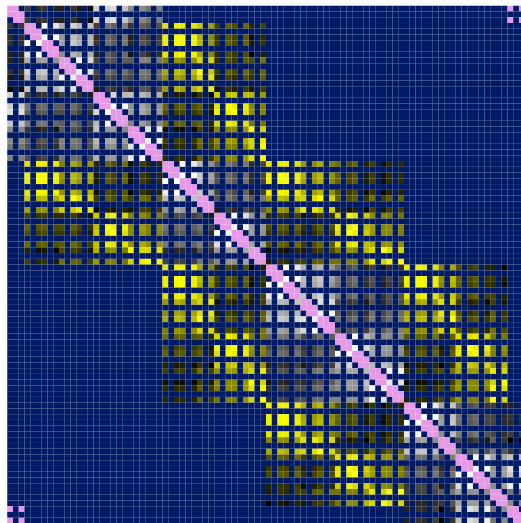
# Application to 3D extrusion additive manufacturing

Minimizing unproductive moves



# 3D additive manufacturing: TSP with special dist. matrix

- Big M distance
- Distance +  $M/10$
- Distance proportionnal to darkness
- Distance = 0



# Application of LKH to 3D printing

- Difference (%) of unproductive length between LKH-2.0.7 and new version with POPMUSIC candidate edges
- Head cleaning every 2 layers

Instance	1	2	3	4	5	6	7	8
Size	4338	5427	4503	3669	13359	6606	6066	10872
Difference	-0.4	0.6	0.7	0.7	-0.8	0.1	1.4	0.9






- Comparison with specially designed methods 1 & 2 of (Volpato et al. 2019 [12]) on instances with cleaning every 2 layers
- Measure : Improvement (%) relatively to solutions of methods 1 & 2

Instance	1	2	3	4	5	6	7	8
Size	2574	2997	3159	3516	6696	4122	6834	6513
Method 1	8.8	30.2	24.0	4.6	38.9	20.8	24.3	11.7
Method 2	6.9	24.6	22.4	1.4	29.7	11.4	15.6	9.6



# Conclusions

- New  $n \log n$  method providing an excellent edge filtering for the TSP
  - Euclidean instances
  - 2D, 3D, 4D Toroidal distances
  - Clustered TSP
  - Special distances for 3D Printing
- Direct application of the method
  - Large instances that must be solved with a limited computational power
  - Drone survey
- How to filter data for other problems ?
  - Seems not evident for the QAP

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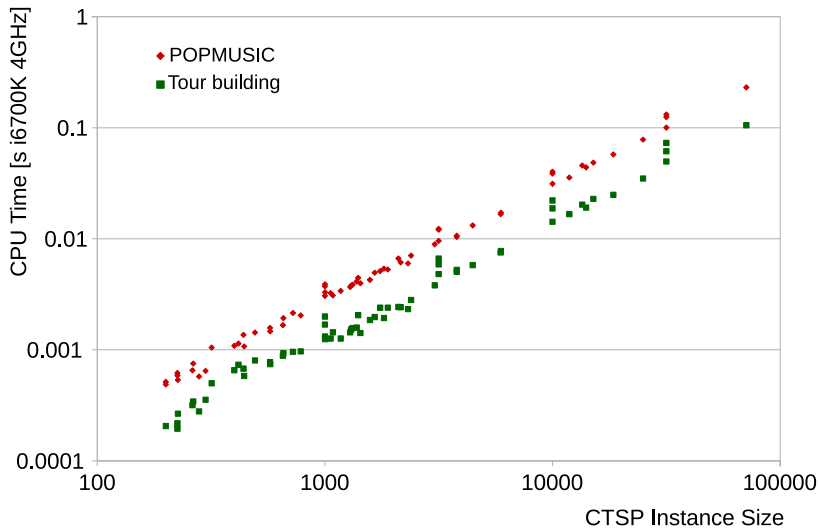


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# Application to the Clustered TSP



# 3D additive manufacturing: Comparing solutions Part4

